| Project Title: | Design, Production, and Testing of a Reaching-Assistant Tool with an Adjustable Length |
|------------------|--|
| Team Members: | Logan Dant David Doctor Justin Kantz |
| Faculty Advisor: | Dr. Libii |
| Area: | Mechanical Engineering |
| Sponsored by: | CME Department |

There is a need for an extendable reaching assistant in the market place, which the design group would like to fill. A reaching assistant is a device that allows the user to essentially extend the reach of their hand. People with back problems, mobility issues, small stature, and so forth, however, have problems using fixed-length assistants, due to the wide range of distances one might want to pick objects up from. In order to facilitate the needs of this group of people, a reaching assistant will be designed with variable length, allowing the user to optimize the device for personal use.